# MoSculp: Interactive Visualization of Shape and Time





Tali













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Andrew Owens<sup>1,3</sup>

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Jiajun  $Wu^1$ 

Stefanie Mueller<sup>1</sup>

William T. Freeman<sup>1,2</sup>



<sup>1</sup> MIT CSAIL



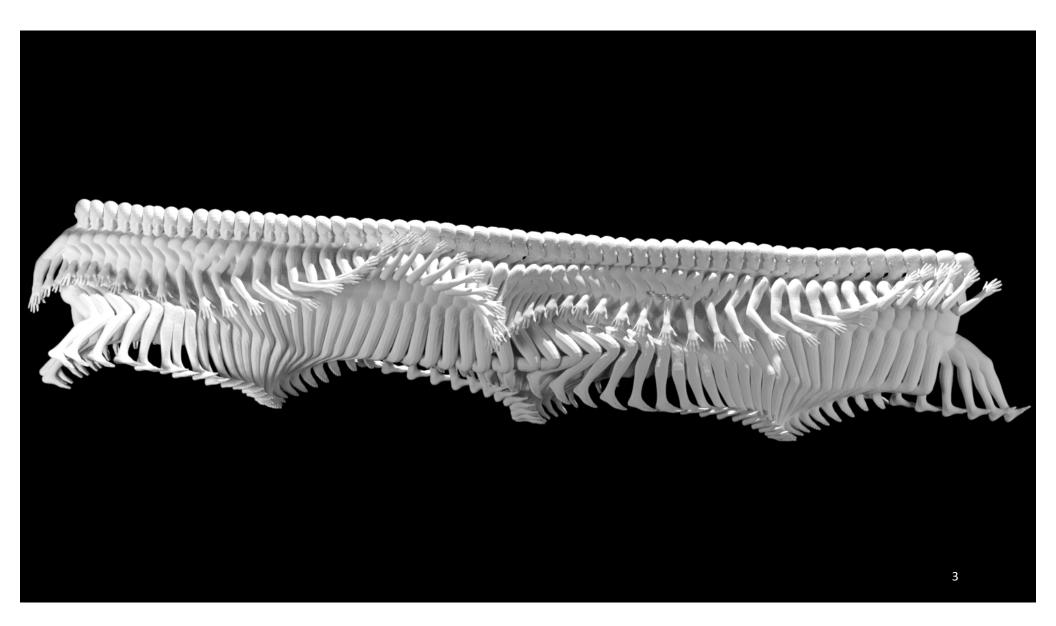
#### <sup>2</sup> Google Research

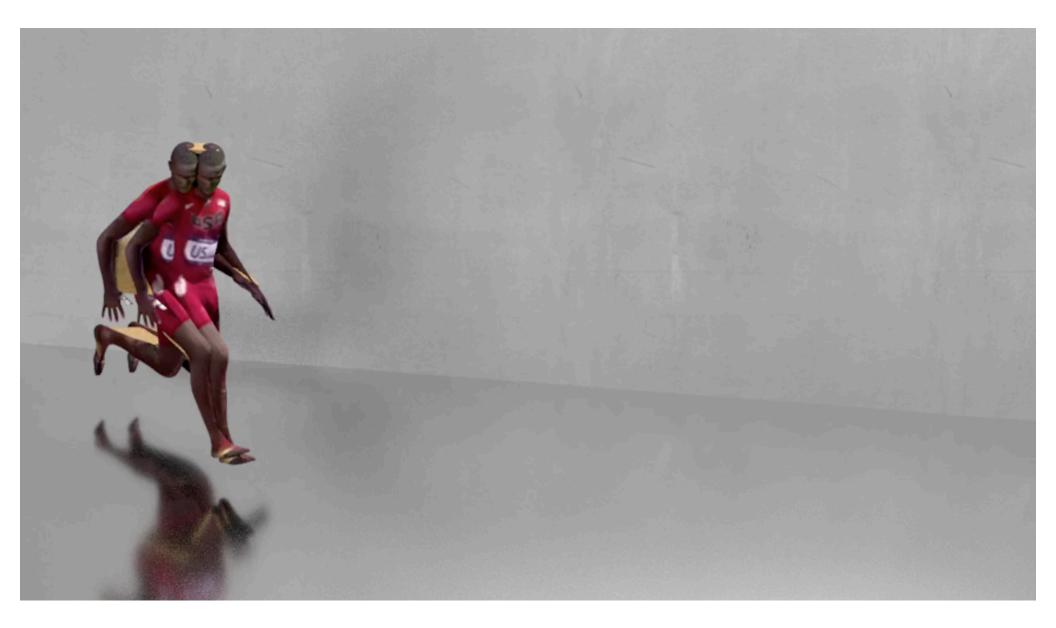


<sup>3</sup> UC Berkeley

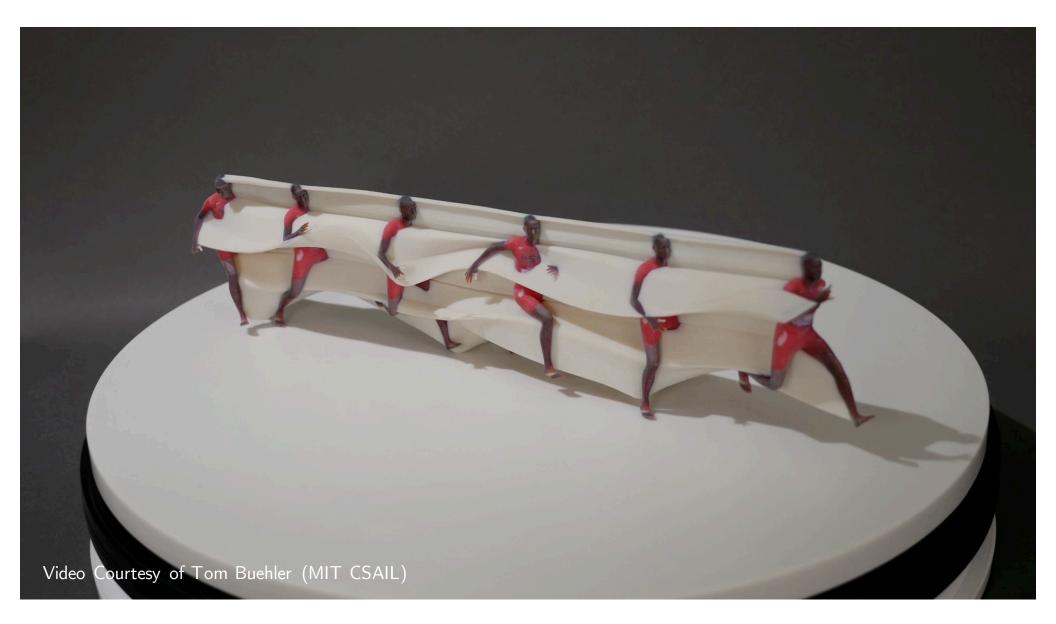










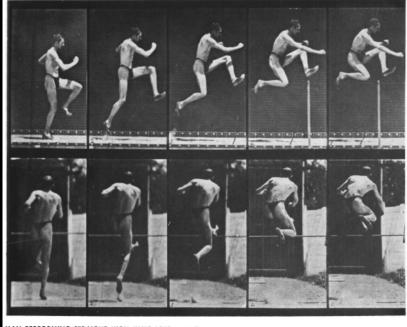


- Related Work
- System Walkthrough
- User Studies
- Approach
- Results
- Conclusion

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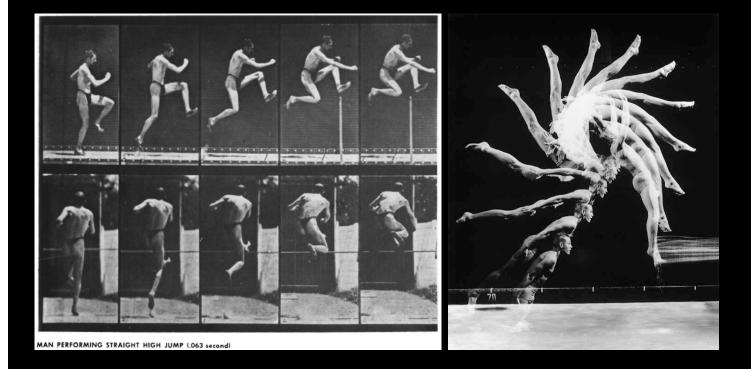
## Motivation



MAN PERFORMING STRAIGHT HIGH JUMP (.063 second)

Muybridge, The Human Figure in Motion, 1901

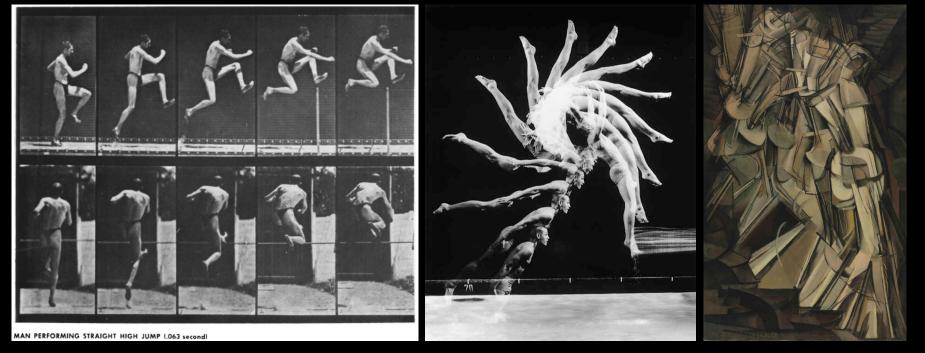
### Motivation



Muybridge, The Human Figure in Motion, 1901

Edgerton, Back Dive, 1954

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Muybridge, The Human Figure in Motion, 1901

Edgerton, Back Dive, 1954

Duchamp, Nude Descending a Staircase, No. 2, 1912 11

## Related Work



Edgerton, *Stroboscopic Photography*, 1927–1931

2D

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Edgerton, *Stroboscopic Photography*, 1927–1931

2D

Freeman & Zhang, *Shape-Time Photography*, CVPR '03

Requires a depth camera

#### Related Work vs. Ours



Edgerton, *Stroboscopic Photography*, 1927–1931

2D

Freeman & Zhang, *Shape-Time Photography*, CVPR '03

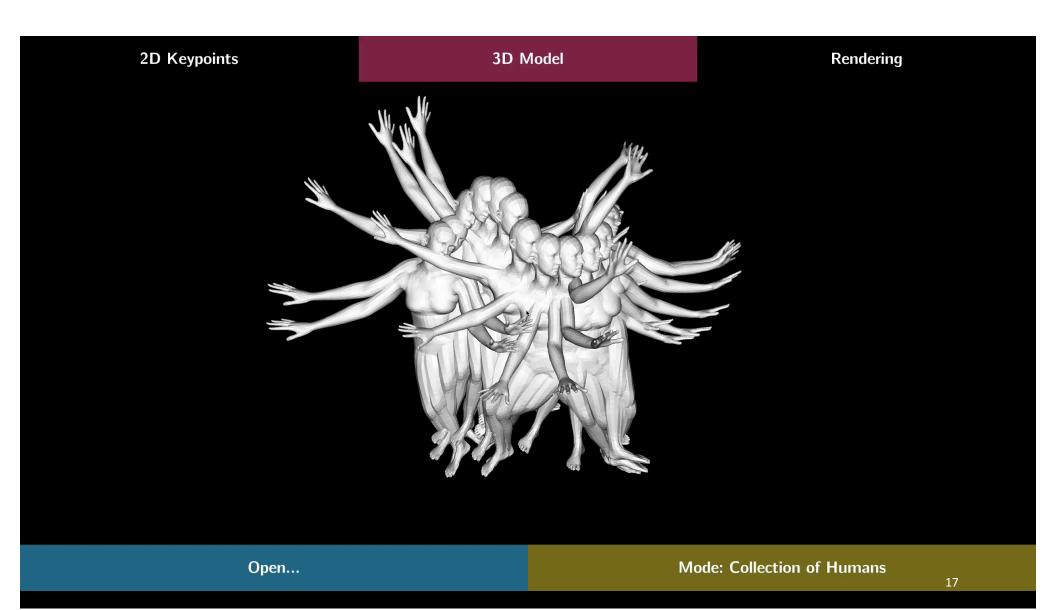
Requires a depth camera

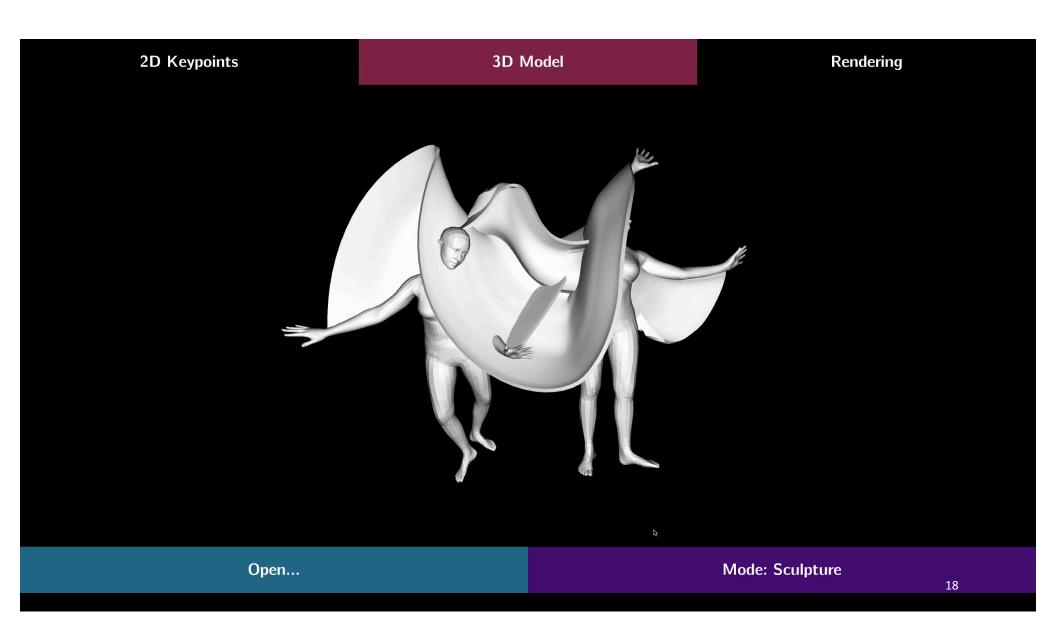
MoSculp

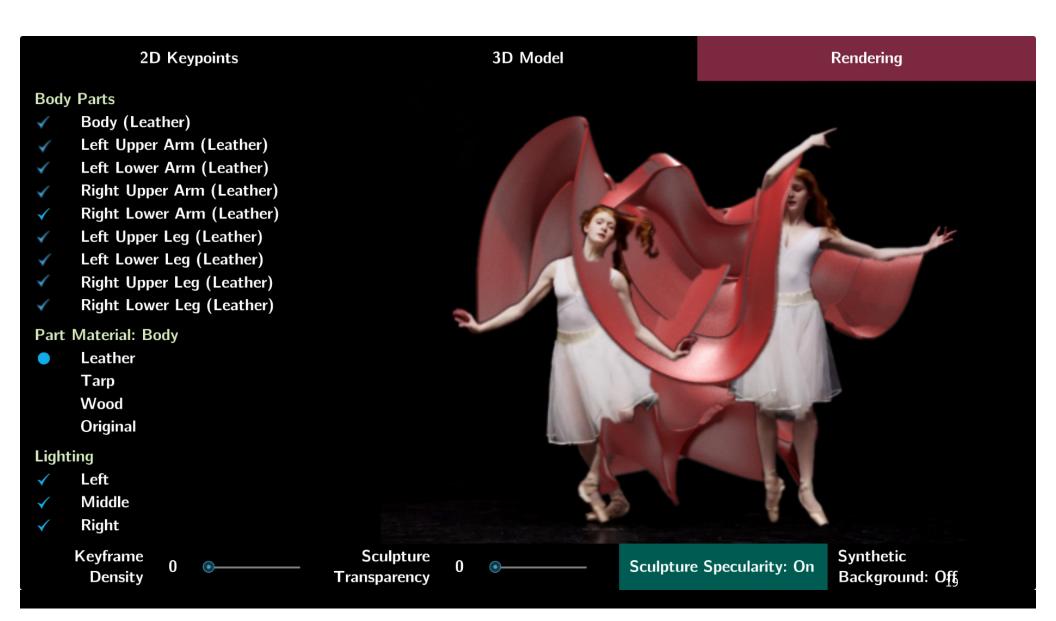
3D w/ an RGB camera

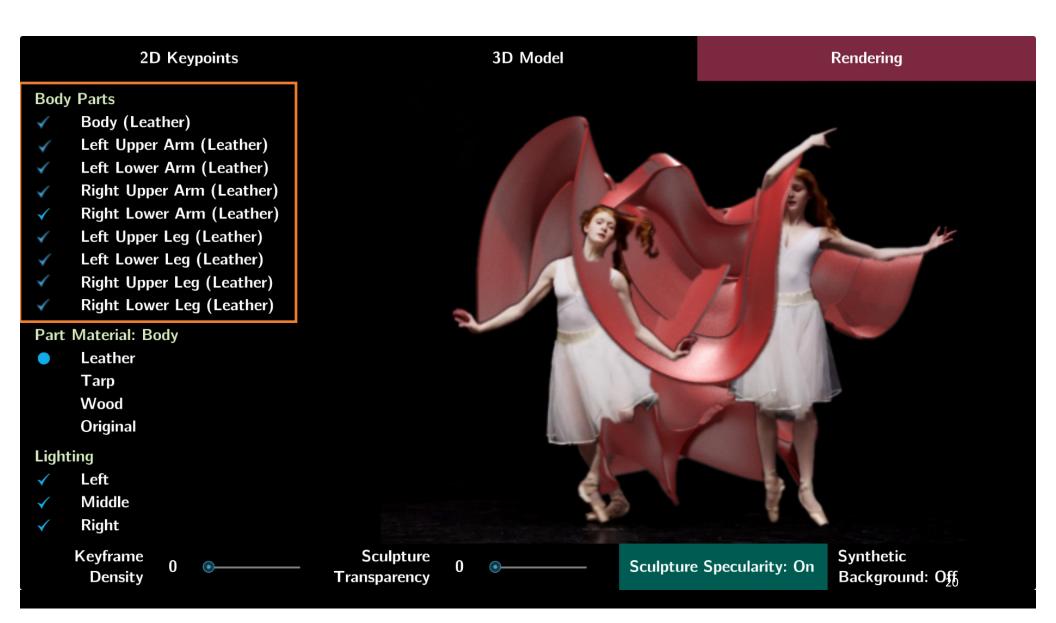
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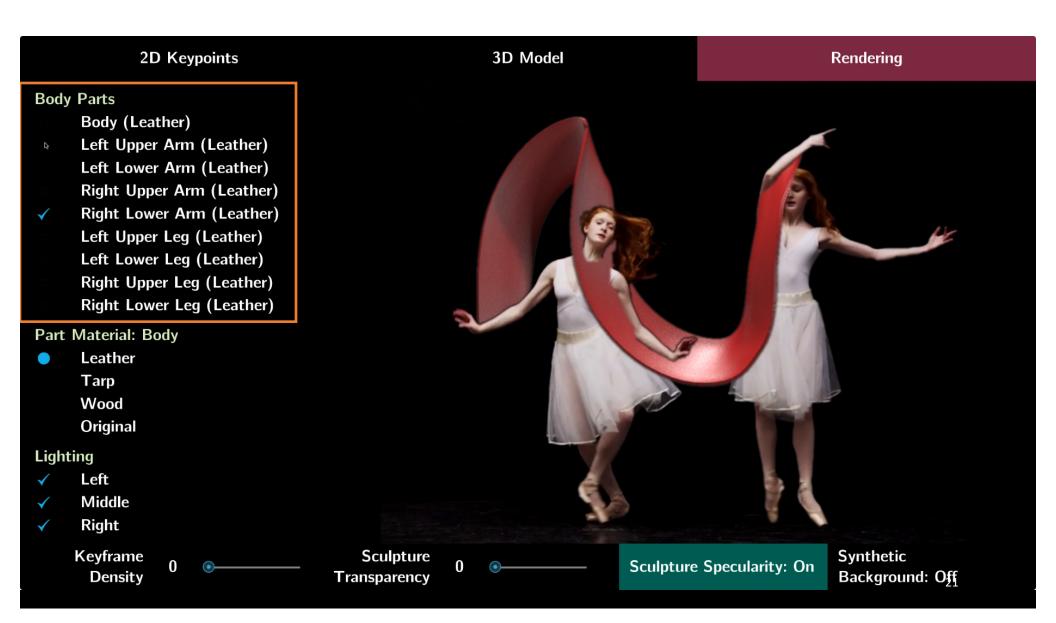


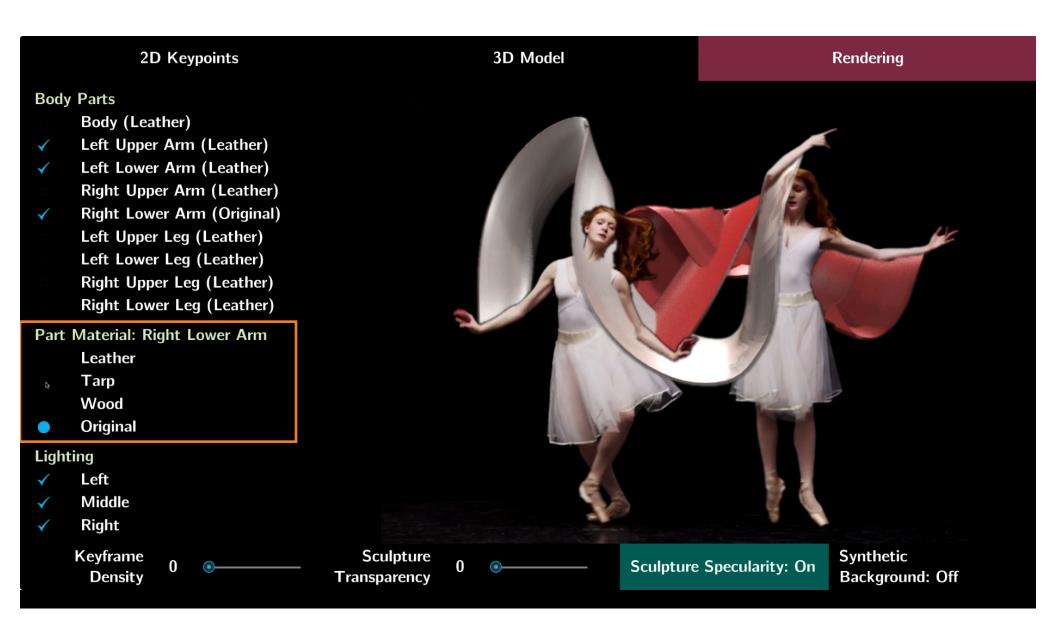


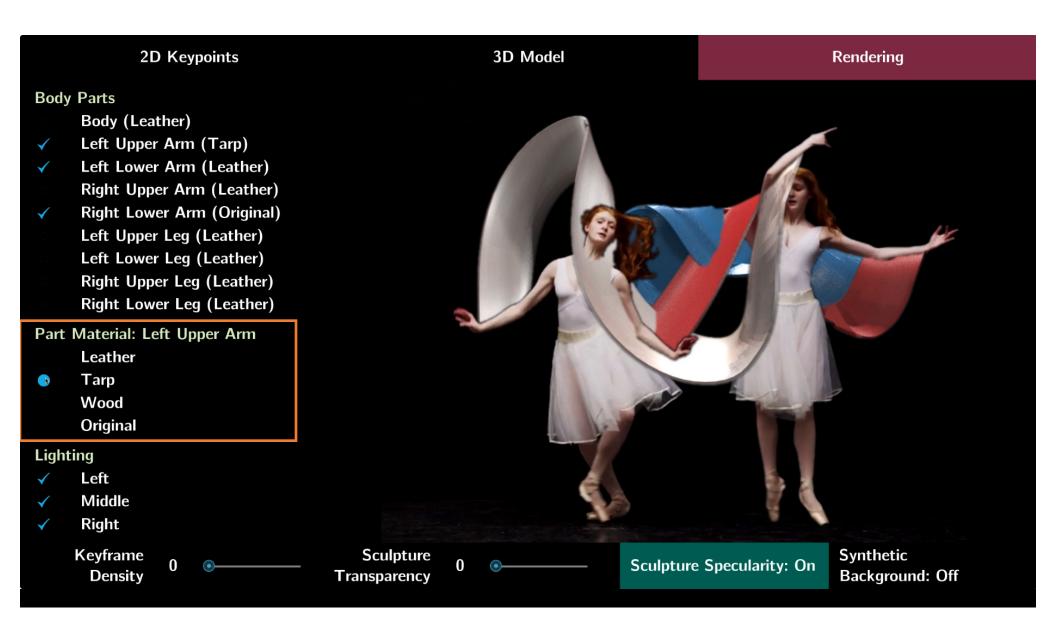


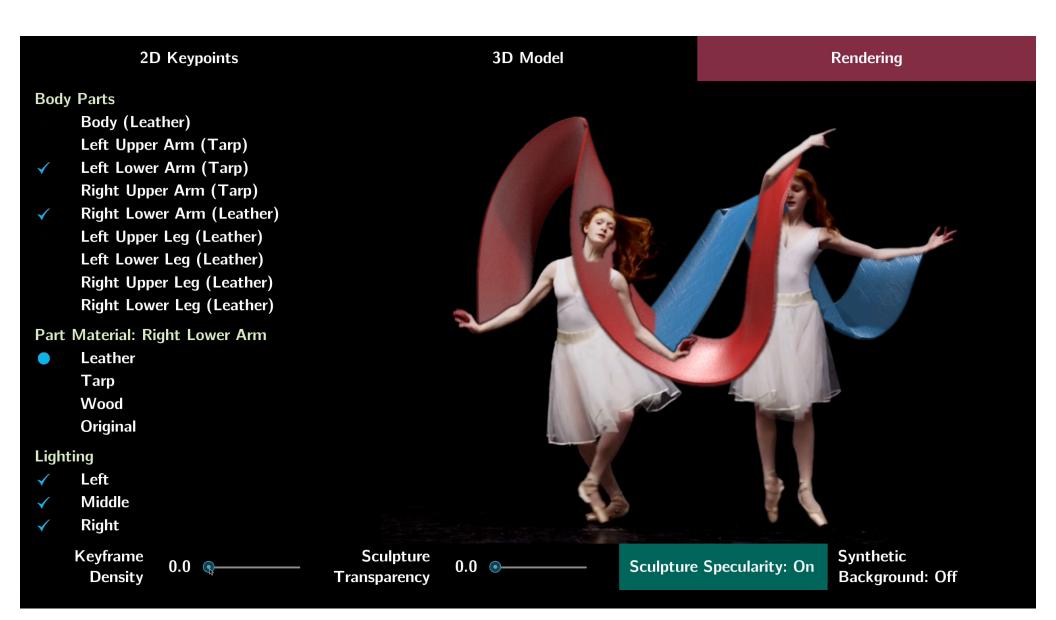


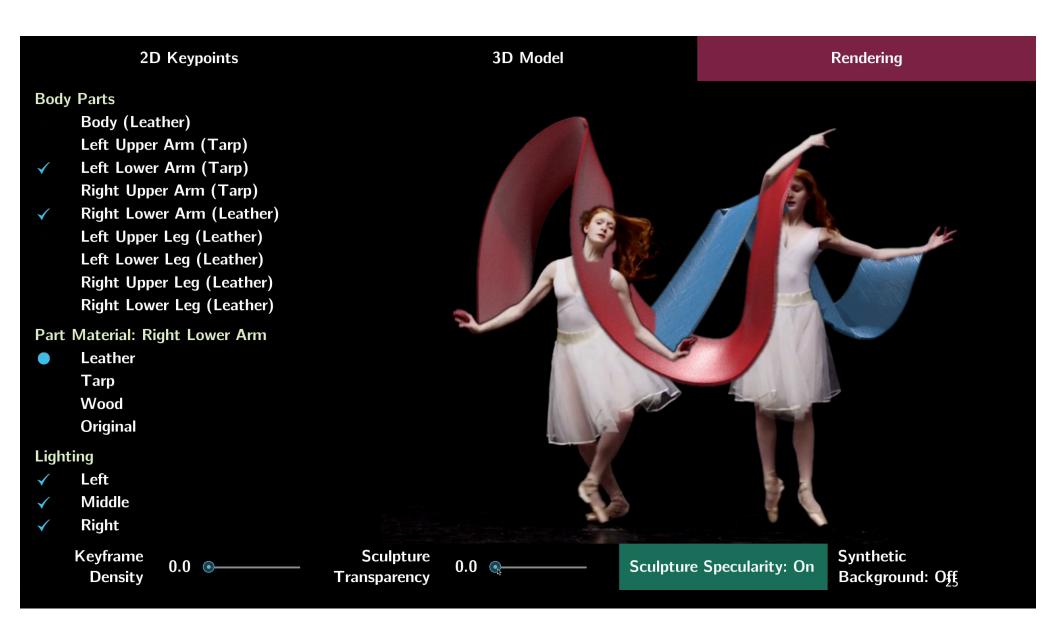












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## User Studies: Design Choices



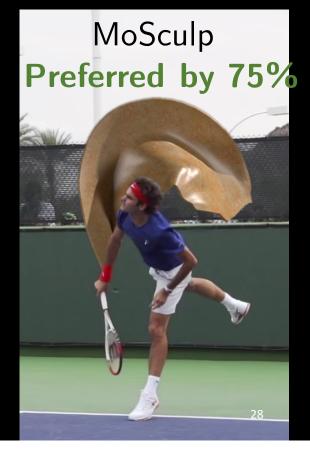


With Floor Reflections Preferred by 82% Without

## User Studies: Efficacy in Conveying Motion



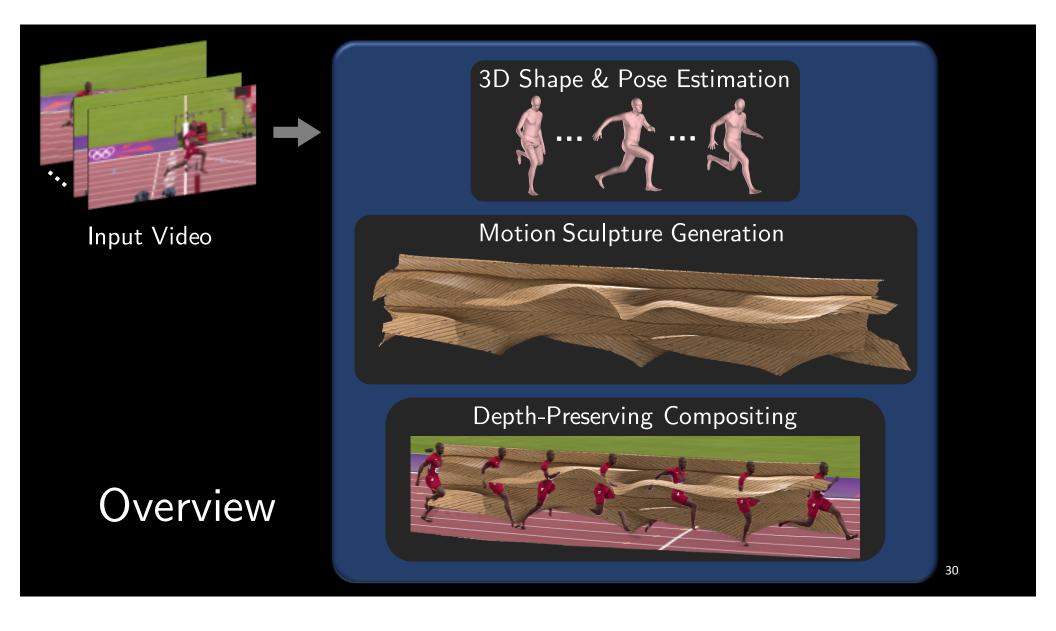


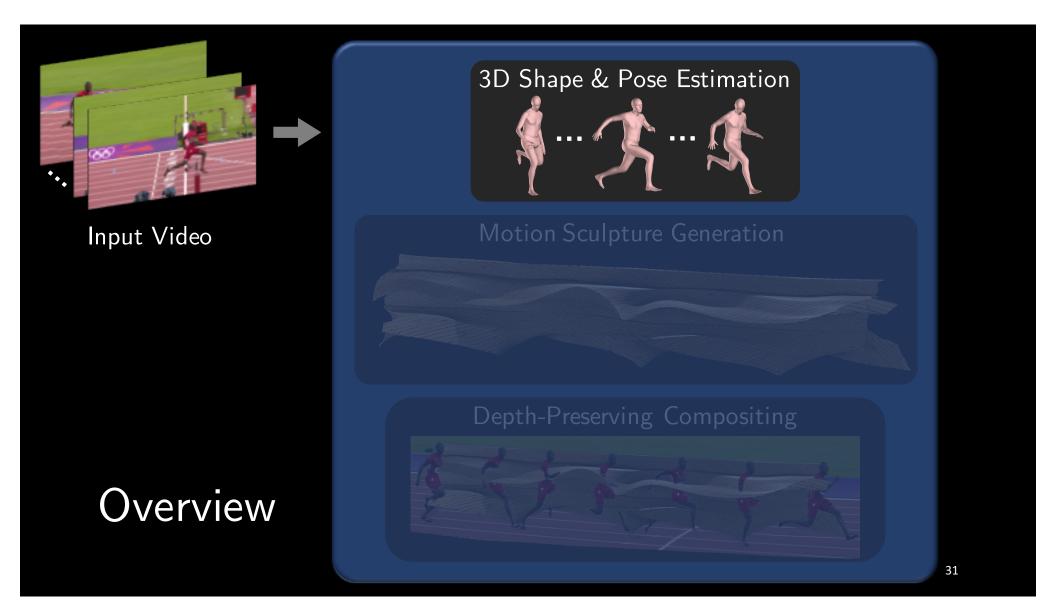


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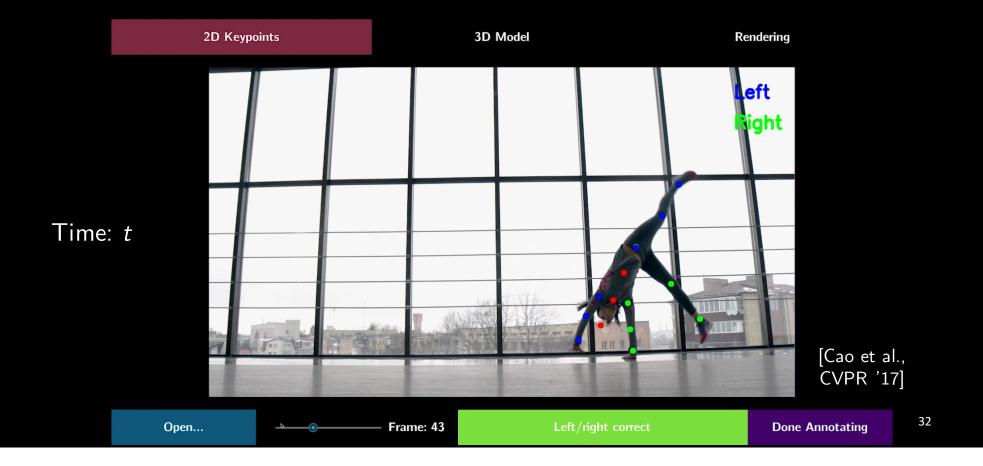
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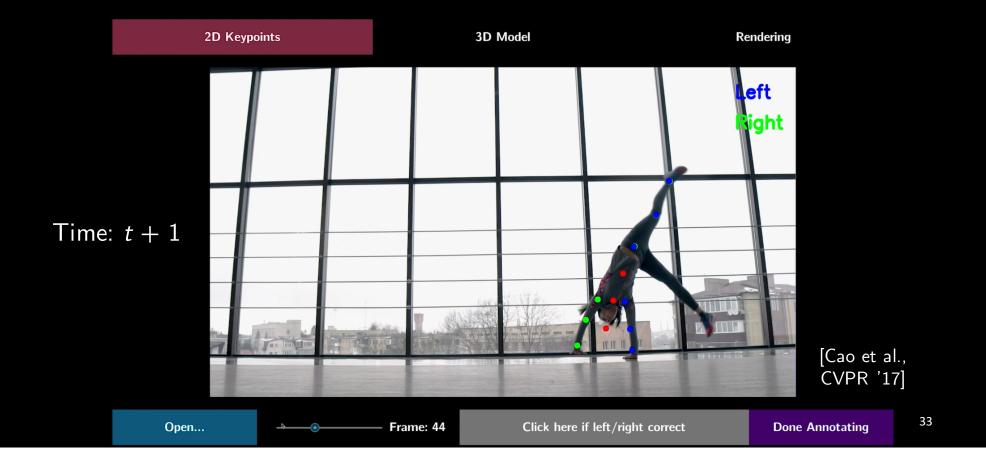


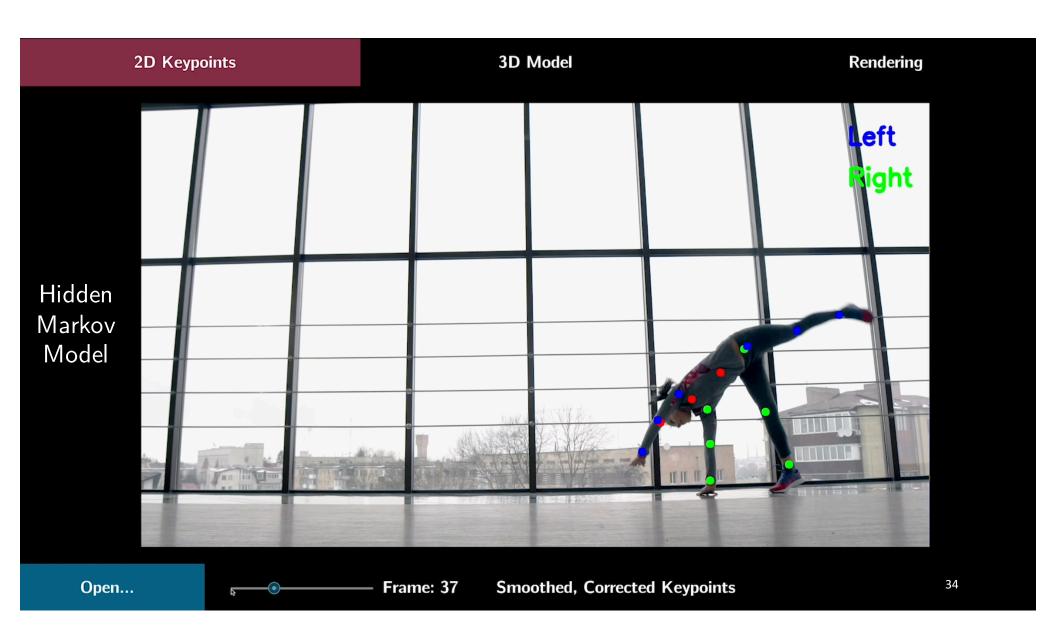


## Approach: 2D Keypoint Detection



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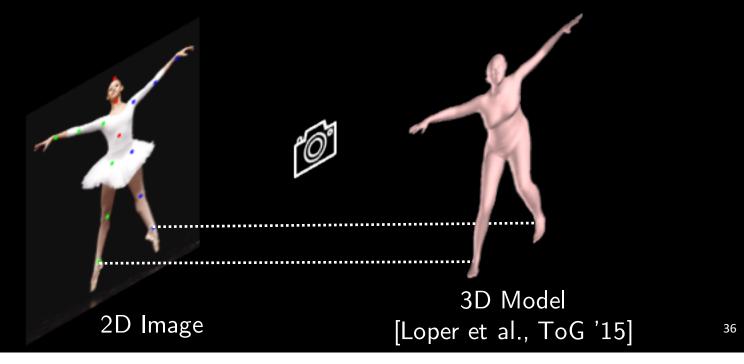




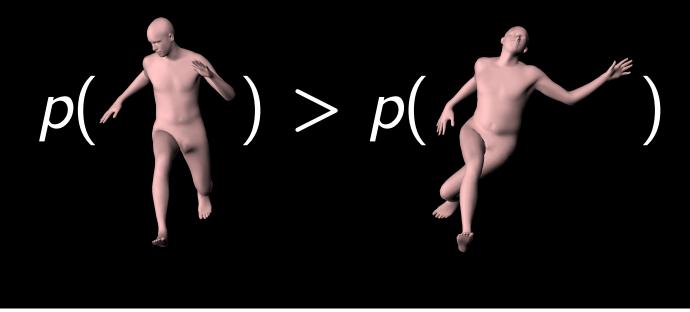
#### Approach: 3D Estimation

• Solve for the best shape and poses jointly for the clip

- Solve for the best shape and poses jointly for the clip
  - Small reprojection error

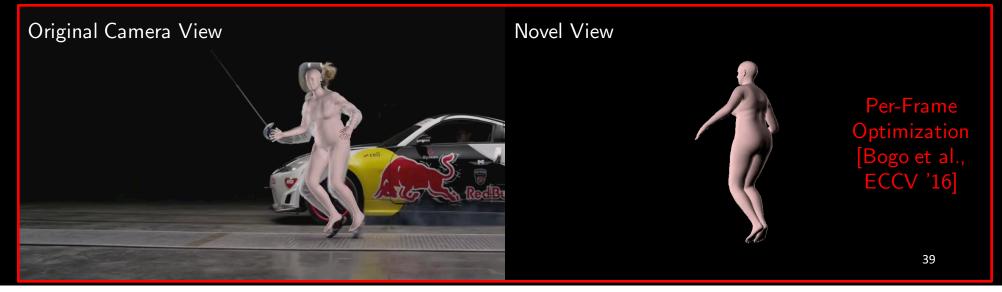


- Solve for the best shape and poses jointly for the clip
  - Small reprojection error
  - Large probability of the poses



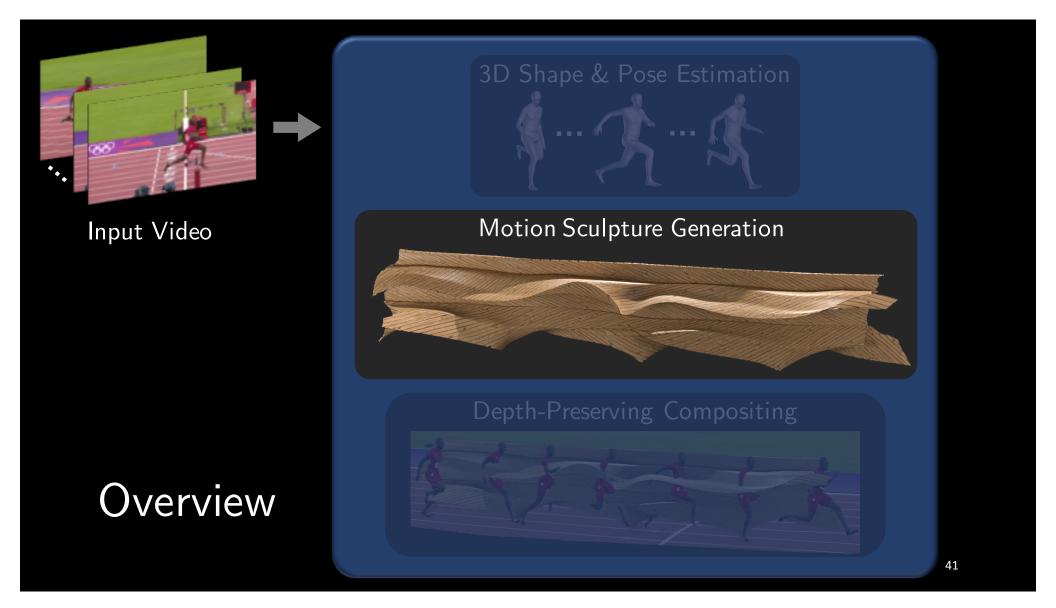
- Solve for the best shape and poses jointly for the clip
  - Small reprojection error
  - Large probability of the poses
  - Smooth evolution of poses

- Solve for the best shape and poses *jointly* for the clip
  - Small reprojection error
  - Large probability of the poses
  - Smooth evolution of poses

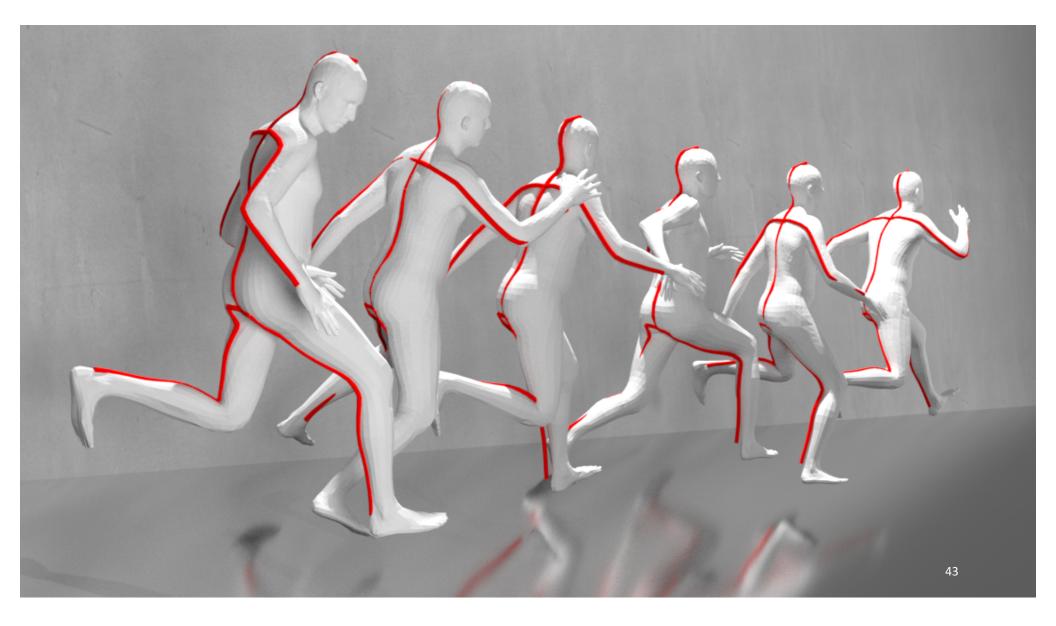


- Solve for the best shape and poses *jointly* for the clip
  - Small reprojection error
  - Large probability of the poses
  - Smooth evolution of poses

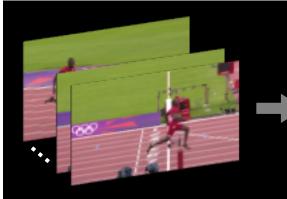












Input Video

## Overview



Motion Sculpture Generation

#### Depth-Preserving Compositing



• **Key challenge**: how to "put together" 3D sculpture and 2D video?

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#### • <u>Naive</u> <u>Compositing</u>: sculpture on top of the frames



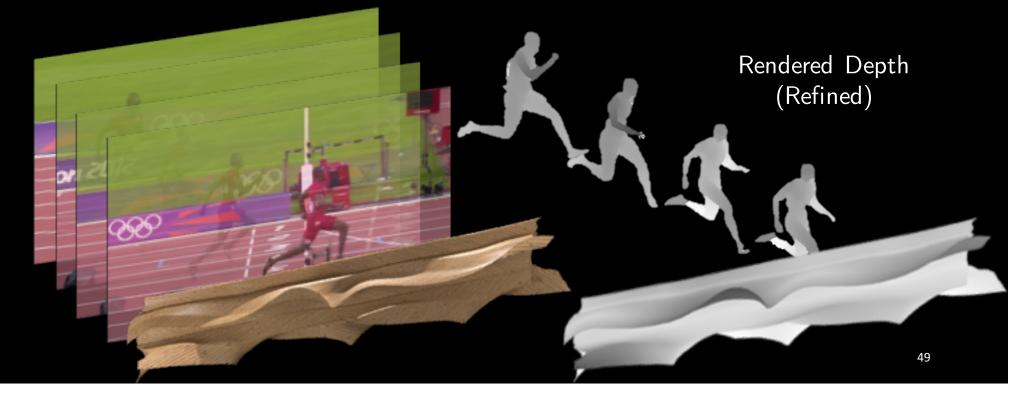
• <u>Full 3D</u> <u>Rendering</u>: texturing the 3D models



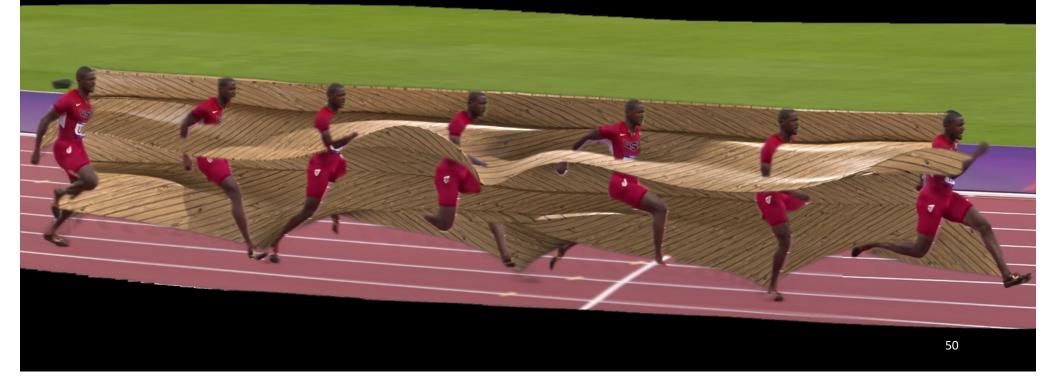
#### Skirt Not Covered by 3D Model

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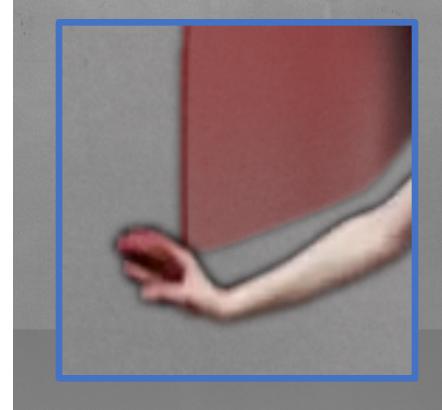
• <u>Solution</u>: depth-preserving composite



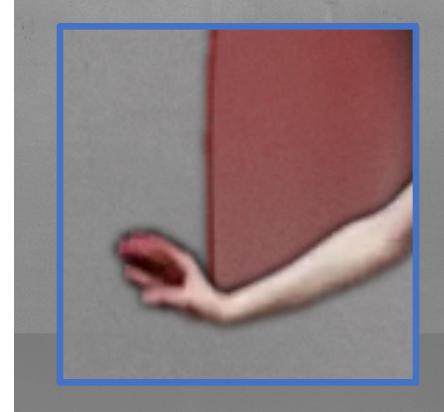
• <u>Solution</u>: depth-preserving composite



## Approach: Before Refinement



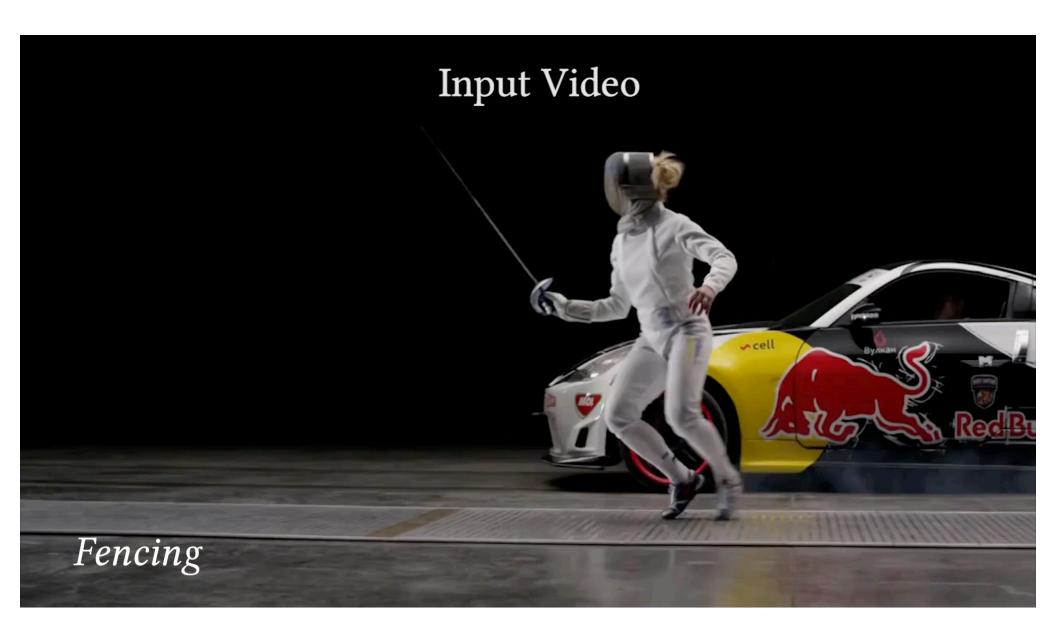
## Approach: After Refinement

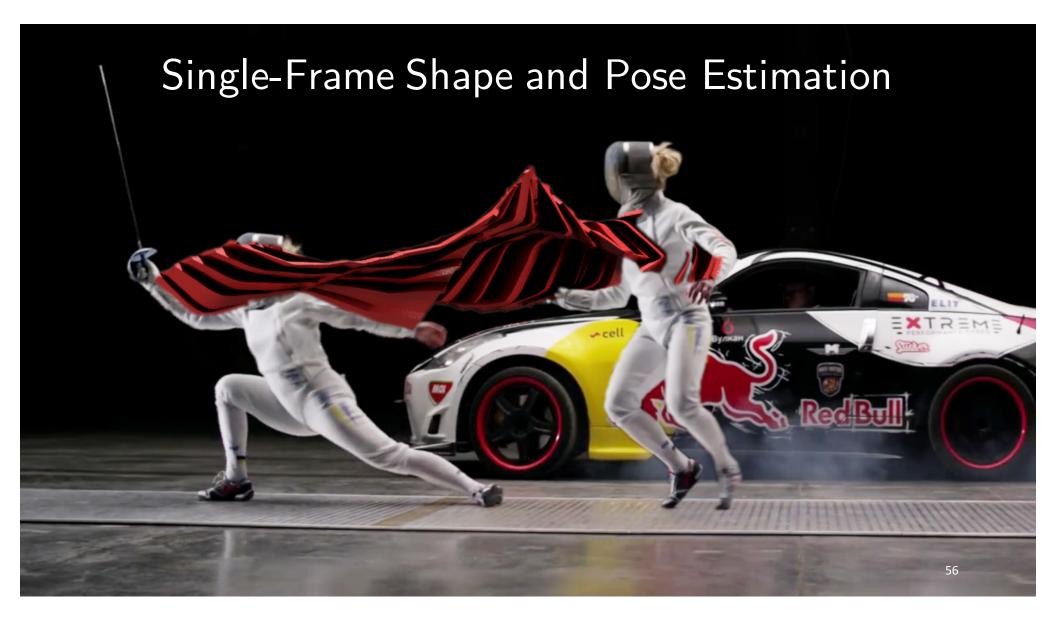


## Outline

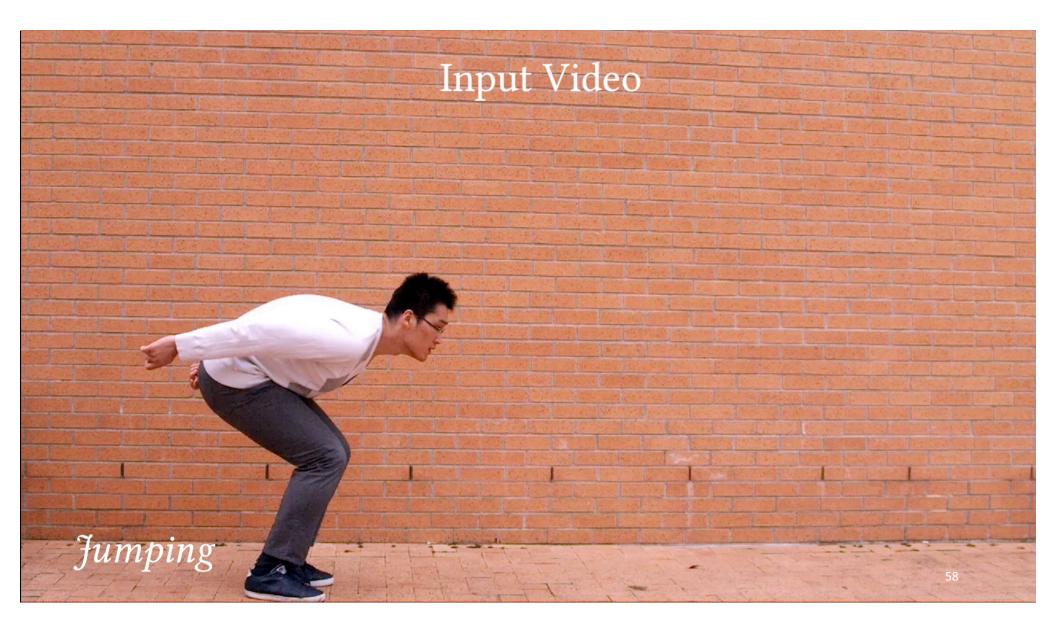
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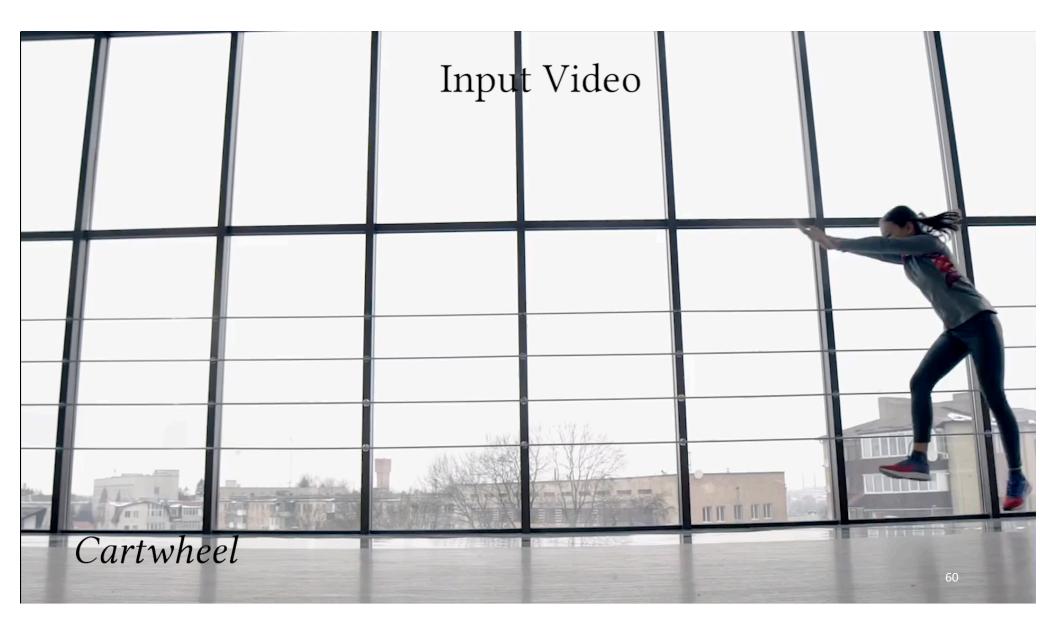


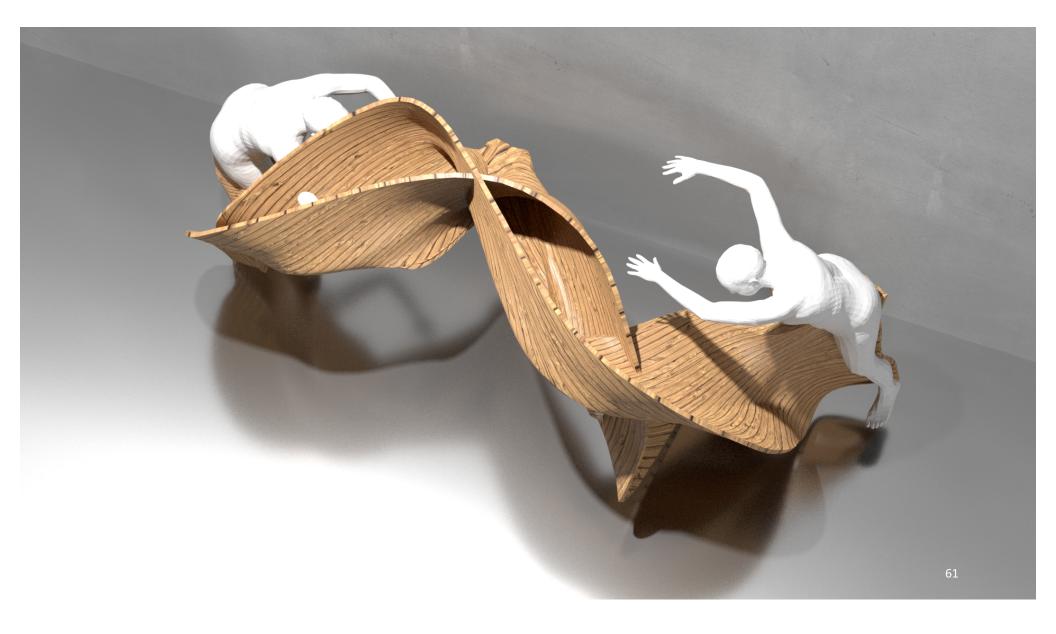


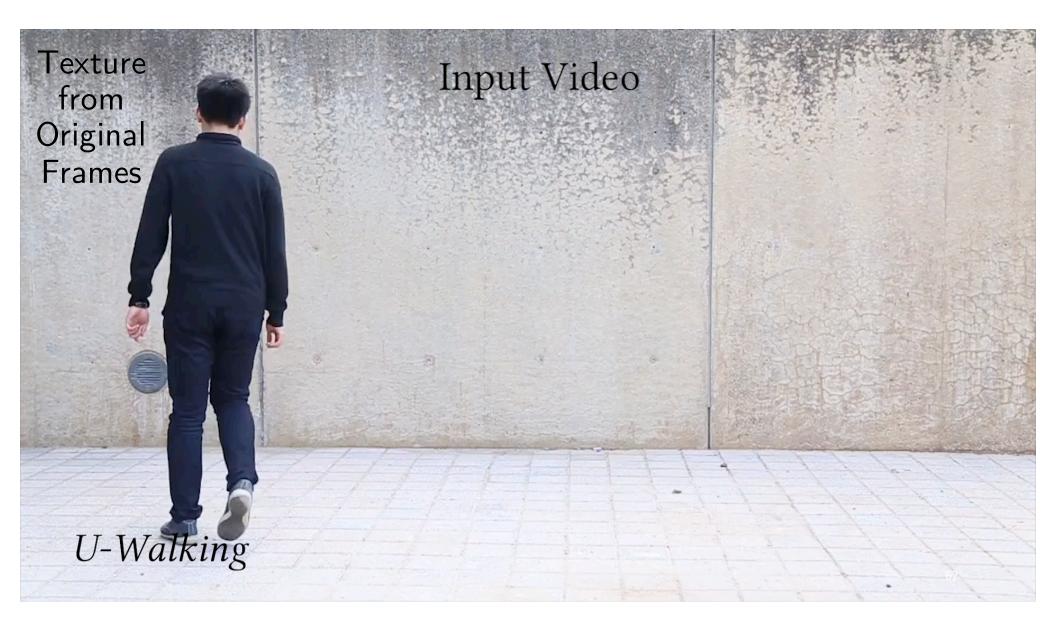


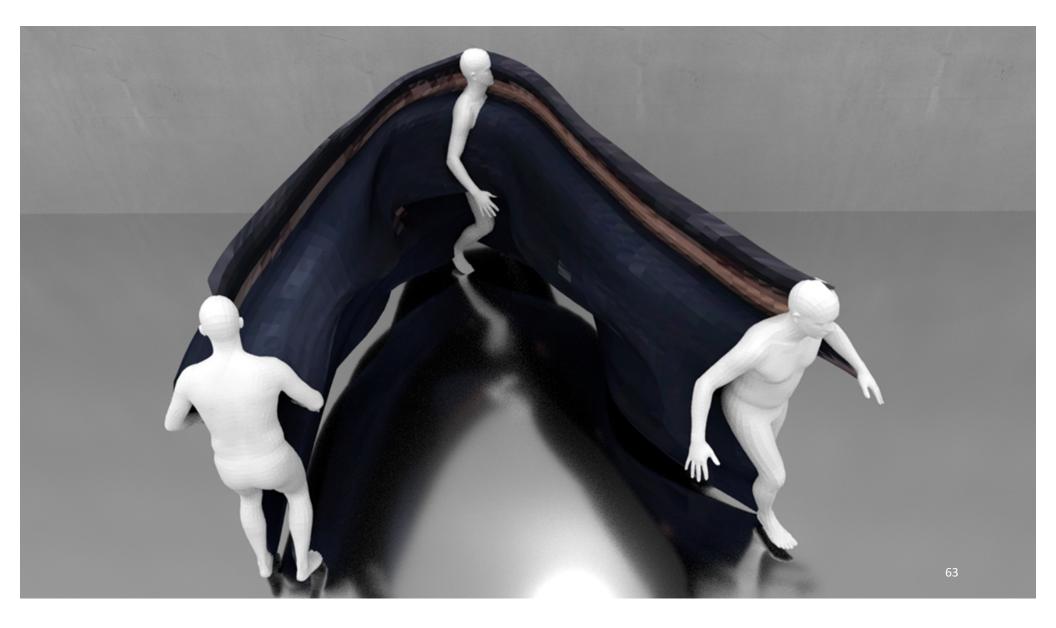


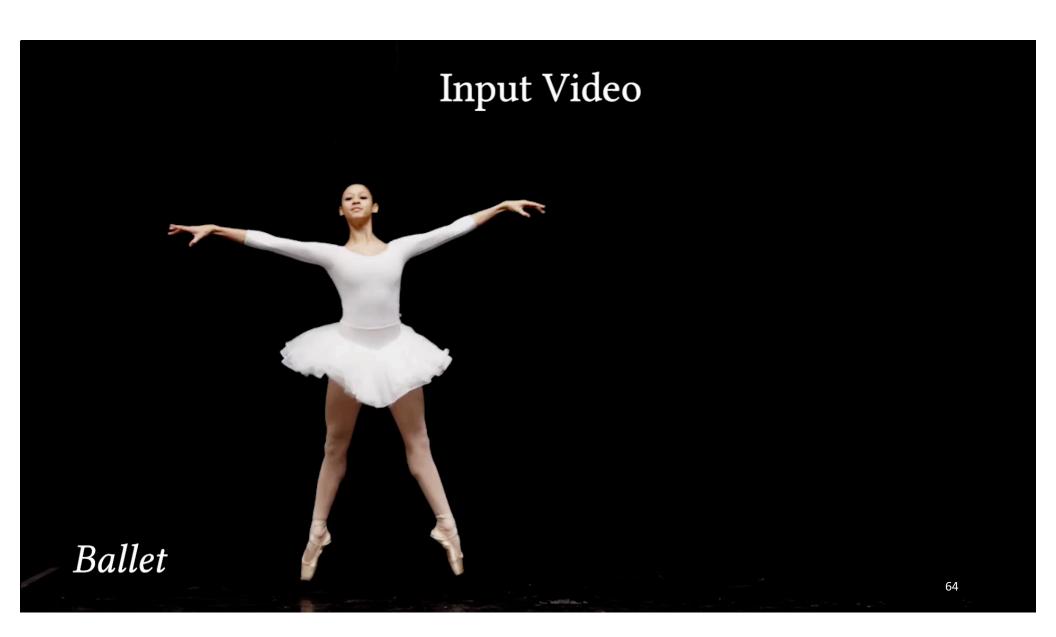














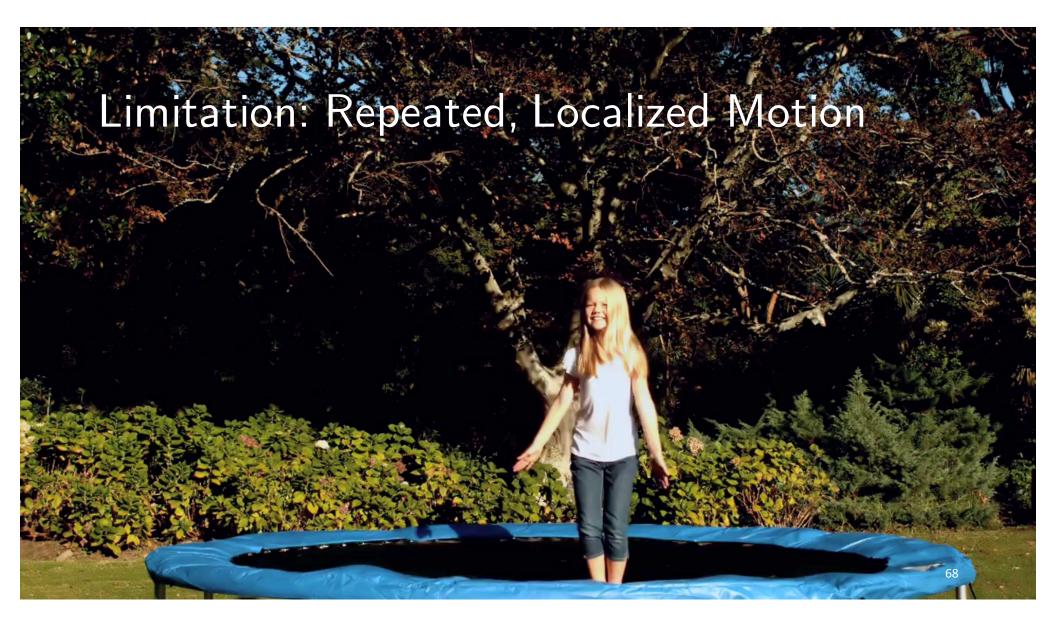
Handling a Moving Camera

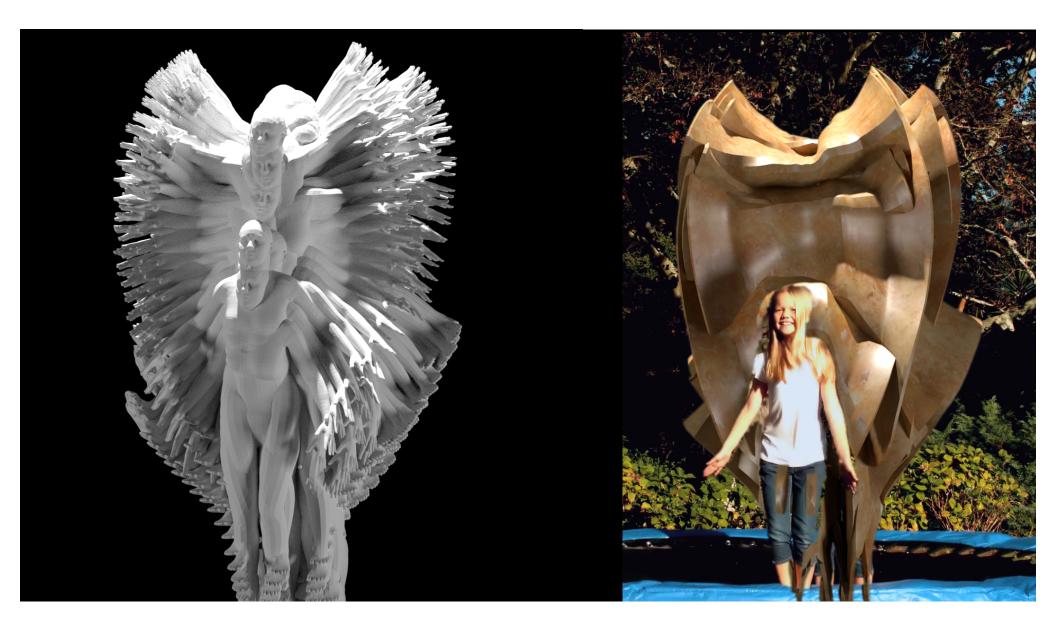
Dunking

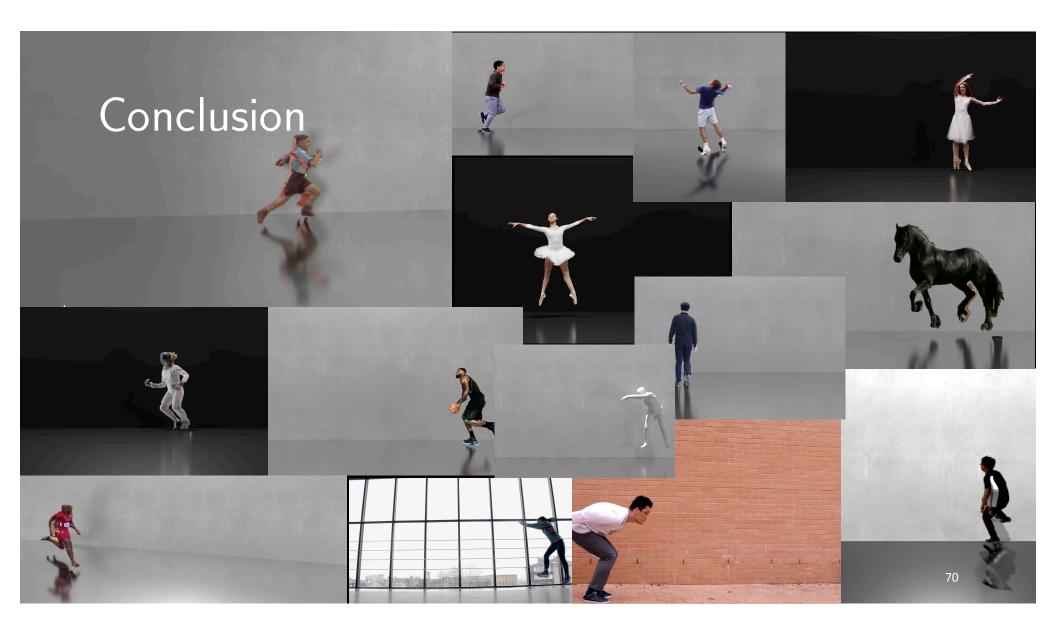


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# http://mosculp.csail.mit.edu Please come to our demo D-12 for more!

#### Thank you!



Video Courtesy of Tom Buehler (MIT CSAIL)